



RT412  
*Optical Transceiver*

User Manual  
(Rev 1.1)



# Contents

<b>Preface</b>	<b>4</b>
<b>Contact</b>	<b>5</b>
<b>Acronyms and Abbreviations</b>	<b>6</b>
<b>1 Description</b>	<b>7</b>
1.1 Introduction . . . . .	7
1.2 Key Features . . . . .	7
1.3 Front and Side View . . . . .	8
1.4 Specifications . . . . .	10
1.4.1 Power Supply . . . . .	10
1.4.2 Electrical Input . . . . .	10
1.4.3 Optical Input . . . . .	10
1.4.4 Electrical Outputs . . . . .	10
1.4.5 Optical Outputs . . . . .	11
1.4.6 Environment . . . . .	11
1.4.7 Weight and Dimensions . . . . .	11
<b>2 Installation</b>	<b>13</b>
2.1 Unpacking . . . . .	13
2.2 External Indications . . . . .	13
2.3 Environment . . . . .	13
2.4 Mounting . . . . .	14
2.5 Connectors . . . . .	14
2.6 Power Supply . . . . .	15
2.6.1 AC Power Connection . . . . .	16
2.6.2 DC Power connection . . . . .	17
2.7 Powering Up . . . . .	17
2.8 Electrical Input . . . . .	18
2.9 Optical Output . . . . .	18
2.10 Jumper to Select Input . . . . .	19
2.11 Electrical Outputs . . . . .	19

2.12 Optical Output . . . . .	20
2.13 Status Indicators . . . . .	20
<b>3 Maintenance</b>	<b>21</b>
3.1 Synchronism Failure . . . . .	21
3.2 Power Supply Failure . . . . .	21
3.3 Cleaning Instructions . . . . .	21
3.4 Returning a Unit . . . . .	21
<b>APPENDIX A - IRIG-B Standard Summary</b>	<b>22</b>
<b>APPENDIX B - Application Example</b>	<b>25</b>

## Preface

© 2013 Reason Tecnologia S.A., all rights reserved.

Products developed by Reason are continuously improved. The information this document contains reflects this improvement, and for this reason it is subject to change without notice. Please make sure that this is latest version of this document before proceeding. All specifications are subject to changes without prior notice.



Certification to the ISO 9001:2008 quality standard is an example of this commitment. We encourage and appreciate any feedback and will use it to improve our products and services.

## About the Document

This manual is intended to technically qualified personnel who has been trained or is knowledgeable in instrumentation and engineering fields.

This user manual is part of the scope of delivery and provides basic information for installation, configuration, operation and maintenance of the equipment here described. In case additional information is needed, please contact Reason at the addresses provided at the beginning of this document.

Document Id: rt412-manual-en  
Revision: 1.1  
Part Number: rt412

According to:  
Hardware Version 04



## Contact

### **Reason Tecnologia S.A.**

Rua Delminda Silveira, 855  
88025-500 Florianópolis, SC  
Brasil

Fone: (48) 2108-0300

Fax: (48) 2108-0310

<http://www.reason.com.br>

### **Reason International, Inc.**

5900 Southwest Parkway, Suite 210  
Austin, TX 78735  
USA

Phone: (512) 615-0490

Fax: (512) 615-0491

<http://www.reason-international.com>

### **RT Measurement Technologies GmbH**

Rudower Chaussee 29  
12489 Berlin  
Germany

Phone: +49 (0)30 57 70 63 32

<http://www.rtgmbh.eu>



## Acronyms and Abbreviations

AC - Alternating Current;

BNC - Bayonet Neil Concelman onnector;

CF - Federal Constitution;

DC - Direct Current;

GND - Ground;

GPS - Global Positioning System;

IEC - International Electrotechnical Commission;

IED - Intelligent Electronic Devices;

IEEE - Institute of Electric and Electronic Engineers;

IHM - Human-Machine Interface;

IP40 - Degree of Protection 40 code;

IRIG-B - Time synchronism protocol (Inter Range Instrumentation Group - Rate Designation B);

OUT - Output;

PPM - Pulse-per-minute;

PPS - Pulse-per-second;

PPX - Pulse-per-X s;

RT - Time recorder (Time synchronism equipment of Reason);

ST - Bayonet-lock connector;

TTL - Transitor-to-transitor logic.

# 1 Description

## 1.1 Introduction

RT412 - Optical Transceiver is an electrical-optical and optical-electrical converter. It converts signals into pulsed signals for time synchronism. Also, the features allow multiplying the outputs of GPS clocks.

The equipment has optical or electrical input, selectable by the user. Also, it has two TTL-level electrical outputs and an optical output. It accepts IRIG-B signals or any other frequency signal (1PPS, 100PPS, 1PPM, inter alia).

The power supply is full range integrated.

The delay of the output signal in relation to the input is under 100 ns.

This User Manual is structured as follows:

Chapter 1 presents RT412 descriptions, its applications, technical specifications, and how the manual is presented.

Chapter 2 presents how RT412 should be installed, considering power supply, cables connections, synchronism outputs, inter alia.

Chapter 3 describes concepts and procedures for maintenance of RT412.

APPENDIX A presents IRIG-B format of signals.

APPENDIX B presents an example of application using equipment for time synchronism.

## 1.2 Key Features

- 100 ns accuracy;
- Integrated optical-electrical and electrical-optical converter;
- ST connector optical Input;
- Time signals in IRIG-B00x format;
- Pulses: 100 pulses-per-second, 1 pulse-per-second, 1 pulse-per-minute and low frequency pulses;
- 2 electrical outputs with screw connector with an individual supply capacity up to 100 mA;
- 1 optical output with ST connector and multimode fiber.
- Indicators for monitoring the input signal of time synchronism and the presence of primary supply;
- DIN rail mounting;
- AC or DC power supply sources.

### 1.3 Front and Side View

The front panel of the RT412 presents its identification, model, and a label with Serial Number and Part Number. Figure 1 shows the front view of the equipment.



Figure 1: RT412 front view

Figure 2 shows the components of the side panel.

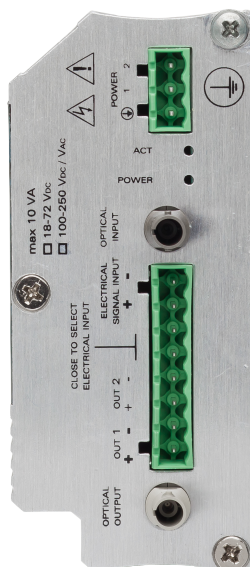


Figure 2: RT412 side view

The side panel of the RT412 comprises one feeding input, AC or DC; two electrical outputs with TTL-level screw connector; an electrical input; a jumper to select the input type; an optical input and output; synchronism signal and power supply indicators.

For information on installing the unit, see Chapter 2.

## 1.4 Specifications

### 1.4.1 Power Supply

Table 1.1: Power Supply Specifications	
Operating voltage range	80–275 V d.c., 88–264 V a.c.
Frequency	50/60 Hz $\pm 3$ Hz
Consumption	< 3 VA

### 1.4.2 Electrical Input

Table 1.2: Electrical Input Specifications	
Connectors (2)	Screw
High Level	4.2 V
Low Level	9.8 V
Impedance	> 500 $\Omega$

### 1.4.3 Optical Input

Table 1.3: Optical Input Specifications	
Wave Length	820 nm
Fiber Type	multimode 50/125 $\mu\text{m}$ , 62.5/125 $\mu\text{m}$ 100/140 $\mu\text{m}$ or 200 $\mu\text{m}$ HCS
Connector	ST
Sensibility	–24 dBm

### 1.4.4 Electrical Outputs

Table 1.4: Electrical Outputs Specifications	
Conectors (4)	Screw (2 outputs)
High Level <sup>1</sup>	> 4 V d.c.
Low Level <sup>2</sup>	< 0.2 V d.c.
Impedance	> 500 $\Omega$
Current	100 mA (for 2 outputs)

<sup>1</sup> Level above which the equipment recognizes output as activated;

<sup>2</sup> Level below which the equipment recognizes output as disabled.

### 1.4.5 Optical Outputs

Table 1.5: Optical Outputs Specifications	
Wave Length	820 nm
Fiber Type	50/125 $\mu\text{m}$ , 62.5/125 $\mu\text{m}$ , 100/140 $\mu\text{m}$ or 200 $\mu\text{m}$ HCS multimode
Connector	ST
Transmission Power	−17.8 dBm (50/125 $\mu\text{m}$ ) −14.0 dBm (62.5/125 $\mu\text{m}$ ) −8.5 dBm (100/140 $\mu\text{m}$ ) −5.7 dBm (200 $\mu\text{m}$ HCS)

### 1.4.6 Environment

Table 1.6 Environment Specifications	
Operating temperature	+5 ... +55 °C
Enclosure protection	IP40
Relative humidity	5 ... 95% (noncondensing)
Maximum Altitude	2000 m (6560 ft)

### 1.4.7 Weight and Dimensions

Table 1.7: Weight and Dimensions Specifications	
Height	117 mm
Width	51 mm
Depth	95 mm
Weight	1 Kg

RT412 dimensions are shown in Figure 3.

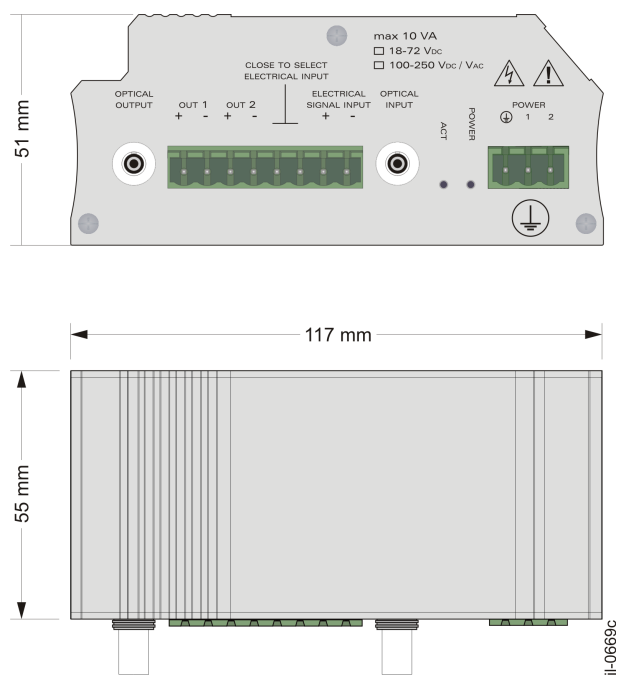


Figure 3: RT412 Dimensions



## 2 Installation

### 2.1 Unpacking

Unpack the unit carefully and make sure all the accessories and cables are put aside so they will not be lost.

Check the contents against the packing list that goes with the product. If any of the content listed is missing, please contact Reason (see contact information at the beginning of this manual).

Examine the unit for any shipping damage. If the unit is damaged or fails to operate, notify the shipping company without delay. Only the consignee (the person or company receiving the unit) can file a claim against the carrier for shipping damage.

We recommend you keep the original packing materials for eventual future transport.

### 2.2 External Indications

The serial number and part number are shown on a label fixed on the side of the unit, as shown in Figure 4.



Figure 4: Location of Serial number and Part Number

### 2.3 Environment

Temperature and relative humidity should not exceed the limits stated in Chapter 1. We recommend providing appropriate heating or cooling measures to ensure that these limits are respected at all times.

## 2.4 Mounting

RT412 has been designed to be mounted on DIN rails. A support bracket, shown in Figure 5, must be used.

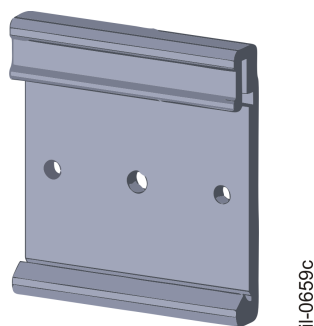


Figure 5: Support bracket to assemble the unit on DIN rails

For more information about dimensions of the unit, see Chapter 1.

## 2.5 Connectors

All RT412 components and connectors are shown in Figure 6.

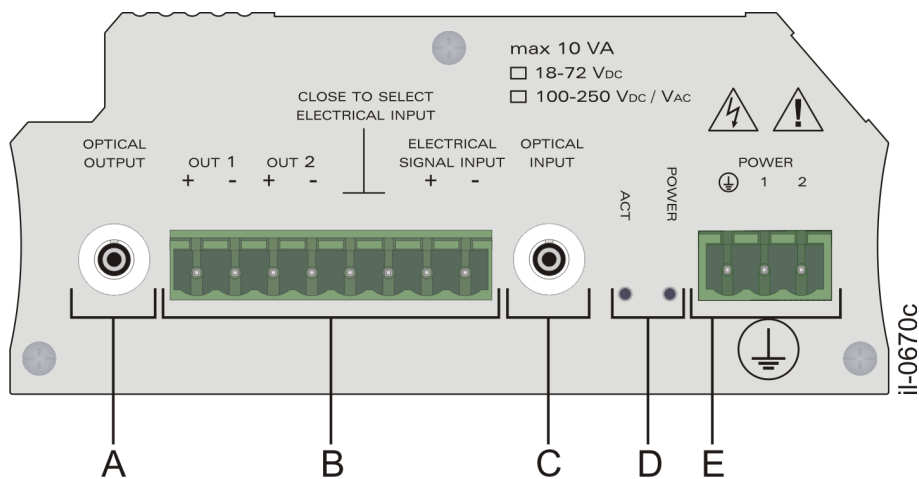


Figure 6: RT412 connectors

**A** Optical output;

**B** 2 screw connector electrical outputs for synchronism; a jumper to select the type of input; an electrical input for synchronism;

**C** Optical input;

**D** RT412 indicators:

- The ACT indicator will light up as soon as signal of one of the synchronism inputs is detected.
- The POWER indicator will light up if a primary power supply is connected to the unit.

**E** AC or DC input.

## 2.6 Power Supply

The unit can be powered from DC or AC power within the limits specified in Chapter 1.

All power connections should use insulated flameproof flexible cable (BWF type) with a 1.5 mm<sup>2</sup> cross section, 70°C thermal class, and 750 V insulation voltage.

To reduce the risk of electrical shock, pre-insulated tubular pin terminals should be used in the ends of power connections.

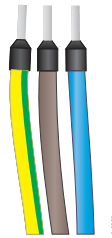


Figure 7: Pre-insulated tubular pin terminals

The pin terminals should be completely inserted into the connectors supplied with the unit, so that no metallic parts are exposed. Refer to the figure below to insert it correctly:

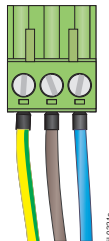


Figure 8: Supply connector assembly

A 1.5 mm<sup>2</sup> ground lead shall be connected to the terminal marked with the protective earth symbol for safety.

For optimal electromagnetic compatibility, ground the unit by using a 10 mm wide grounding strap to connect the frame of the unit to a good ground point on the mounting rack.

### 2.6.1 AC Power Connection

Phase should be applied to terminal 1 and neutral to terminal 2 in each of the supply terminals identified as POWER, as shown in Figure 9.

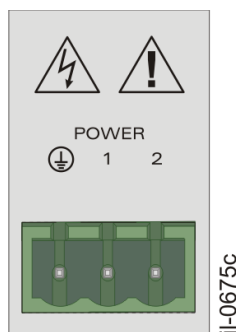


Figure 9: AC power connection

The installation of an external 10 A, category C, unipolar circuit breaker near the unit is recommended. The circuit breaker should have an interruption capacity of at least 25 kA and comply with IEC 60947-2 standard.

### 2.6.2 DC Power connection

Positive should be applied to terminal 1 and negative to terminal 2 in each of the supply terminals identified as POWER, as shown in Figure 10.

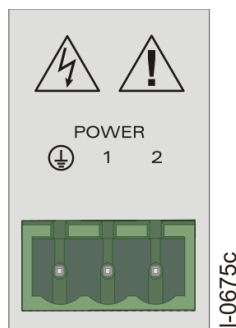


Figure 10: DC power connection

The installation of an external 10 A, category C, unipolar circuit breaker near the unit is recommended. The circuit breaker should have an interruption capacity of at least 25 kA and comply with IEC 60947-2 standard.

## 2.7 Powering Up

1. Before energizing the unit, be familiarized with all the DANGER and ATTENTION indicators in the eq.
2. Connect the power supply (including the ground lead) to the appropriate terminals. After connecting the power supply, the POWER indicator will light up.
3. To turn off the unit, disconnect the power supply (including the ground lead) from the terminals. All front panel indicators will turn off.

In case the unit does not behave in a way here described, carefully check all power and signal connections. See Chapter 3 for additional suggestion for problem diagnosis.

## 2.8 Electrical Input

RT412 has an electrical input with screw connector, to be used as electrical-optical converter, identified as ELECTRICAL SIGNAL INPUT, as shown in Figure 11.

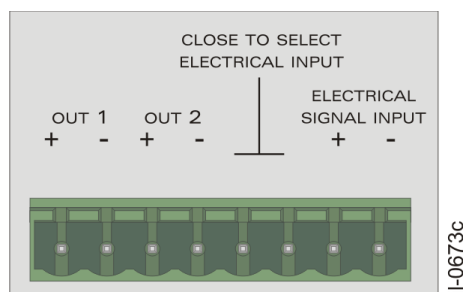


Figure 11: TTL level electrical input

The input accepts demodulated IRIG signals, 1PPS, 1PPM, 100PPS, or low frequency pulses. The signal inserted in the selected input is sent to the electrical and optical outputs.

To use the electrical input, the jumper must be connected according to the Section 2.10.

## 2.9 Optical Output

RT412 has an optical input with BNC connector, to be used as optical-electrical converter, identified as OPTICAL INPUT, as shown in Figure 12.

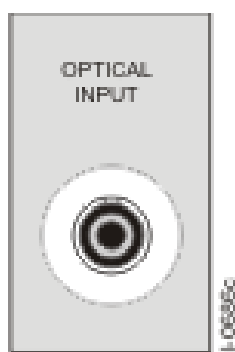


Figure 12: Optical Input

The input accepts demodulated IRIG signals, 1PPS, 1PPM, 100PPS, or low frequency pulses. The signal inserted in the selected input is sent to the electrical and optical outputs.

To use the optical input, the jumper should remain open, according to the Section 2.10.

## 2.10 Jumper to Select Input

RT412 can be used with an optical or electrical input. To select the type of input desired, the following logic must be used:

Table 2.1: Jumper to select the input	
Closed Jumper	Electrical Input
Open Jumper	Optical Input

The jumper to select the input is identified as CLOSE TO SELECT ELECTRICAL INPUT, as show in Figure 13.

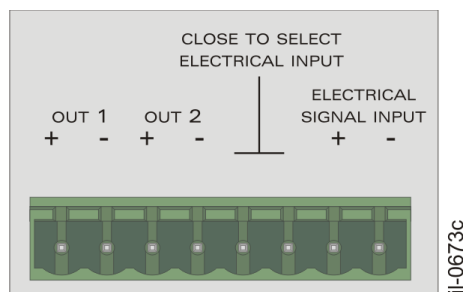


Figure 13: Jumper to select the input

## 2.11 Electrical Outputs

RT412 has 2 screw connector electrical outputs, identified as OUT 1 and OUT 2, according to Figure 14.

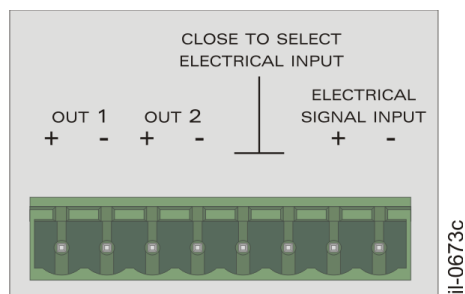


Figure 14: TTL Level electrical outputs

The synchronism signal inserted in the selected input is sent to the electrical and optical outputs.

## 2.12 Optical Output

RT412 has 1 BNC connector optical output, identified as OPTICAL OUTPUT, according to Figure 15.

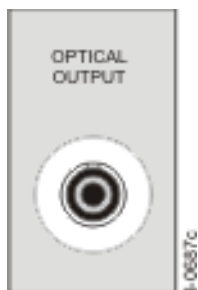


Figure 15: Optical output

The synchronism signal inserted in the selected input is sent to the electrical and optical outputs.

## 2.13 Status Indicators

RT412 has status indicators for monitoring the presence of primary supply and data flow between the synchronism input and output, according to Figure 16.

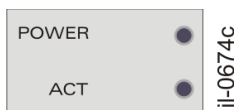


Figure 16: RT412 Status Indicators

The POWER indicator will light up as soon a primary power supply is connected to the unit. In case the power supply is interrupted, the indicator will turn off.

The ACT indicator, when lit, indicates data flow between the input and output.



## 3 Maintenance

### 3.1 Synchronism Failure

When the unit is operating without data flow between the input and output, the ACT indicator will remain off. Every time synchronism failure is detected, the following actions are recommended:

- Make sure the unit is turned on.
- Make sure the electrical or optical-fiber cables are connected properly.
- Make sure the receipt and transmission connectors are not changed.
- Make sure the input configuration (Jumper) is correct.
- Make sure the electrical or optical-fiber cables are in good conditions.
- If possible, do the test using another electrical or optical-fiber cable.
- Make sure the optical-fiber cable is according to the specifications established.

### 3.2 Power Supply Failure

If there is no power supply, the POWER indicator will remain off. When there is voltage failure, the following actions are recommended:

- Make sure the terminals 1, 2 and Ground are connected properly.
- Make sure there is voltage in the power supply terminal.

### 3.3 Cleaning Instructions

Before cleaning the equipment, make sure that the primary voltage is removed. If it is necessary cleaning the exterior of the equipment, use only a dry cloth. Internally it is not required any cleaning.

### 3.4 Returning a Unit

In case repair service is needed, contact Reason to check out the shipment options and receive a technical assistance reference code. To contact Reason, see the Contact section of this manual.

The unit shall be packed in its original package or a suitable package to protect against impacts and moisture.

Identify the package with the technical assistance code and send it to the address supplied.

## APPENDIX A - IRIG-B Standard Summary

### IRIG-B004 and IRIG-B124 content:

Table A.1: IRIG-B standard summary			
0	$P_r$	reference bit ( $P_r$ )	
1	$P_r + 10$ ms	seconds 1	seconds (0 ... 59 or 60)
2	$P_r + 20$ ms	seconds 2	
3	$P_r + 30$ ms	seconds 4	
4	$P_r + 40$ ms	seconds 8	
5	$P_r + 50$ ms	index bit (0)	
6	$P_r + 60$ ms	seconds 10	
7	$P_r + 70$ ms	seconds 20	
8	$P_r + 80$ ms	seconds 40	
9	$P_r + 90$ ms	position identifier 1 ( $P_1$ )	minutes (0 ... 59)
10	$P_r + 100$ ms	minutes 1	
11	$P_r + 110$ ms	minutes 2	
12	$P_r + 120$ ms	minutes 4	
13	$P_r + 130$ ms	minutes 8	
14	$P_r + 140$ ms	index bit (0)	
15	$P_r + 150$ ms	minutes 10	
16	$P_r + 160$ ms	minutes 20	
17	$P_r + 170$ ms	minutes 40	hours (0 ... 23)
18	$P_r + 180$ ms	index bit (0)	
19	$P_r + 190$ ms	position identifier 2 ( $P_2$ )	
20	$P_r + 200$ ms	hours 1	
21	$P_r + 210$ ms	hours 2	
22	$P_r + 220$ ms	hours 4	
23	$P_r + 230$ ms	hours 8	
24	$P_r + 240$ ms	index bit (0)	
25	$P_r + 250$ ms	hours 10	day of the year (1 ... 365 or 366)
26	$P_r + 260$ ms	hours 20	
27	$P_r + 270$ ms	index bit (0)	
28	$P_r + 280$ ms	index bit (0)	
29	$P_r + 290$ ms	position identifier 3 ( $P_3$ )	
30	$P_r + 300$ ms	days 1	
31	$P_r + 310$ ms	days 2	
32	$P_r + 320$ ms	days 4	
33	$P_r + 330$ ms	days 8	
34	$P_r + 340$ ms	index bit (0)	
35	$P_r + 350$ ms	days 10	
36	$P_r + 360$ ms	days 20	
37	$P_r + 370$ ms	days 40	
38	$P_r + 380$ ms	days 80	
39	$P_r + 390$ ms	position identifier 4 ( $P_4$ )	

40	$P_r + 400$ ms	days 100	two digits of the year (00 ... 99)
41	$P_r + 410$ ms	days 200	
42	$P_r + 420$ ms	index bit (0)	
43	$P_r + 430$ ms	index bit (0)	
44	$P_r + 440$ ms	index bit (0)	
45	$P_r + 450$ ms	index bit (0)	
46	$P_r + 460$ ms	index bit (0)	
47	$P_r + 470$ ms	index bit (0)	
48	$P_r + 480$ ms	index bit (0)	
49	$P_r + 490$ ms	position identifier 5 ( $P_5$ )	
50	$P_r + 500$ ms	year 1	1 during the minute that precede the beginning or the end of DST
51	$P_r + 510$ ms	year 2	
52	$P_r + 520$ ms	year 4	
53	$P_r + 530$ ms	year 8	
54	$P_r + 540$ ms	index bit (0)	
55	$P_r + 550$ ms	year 10	
56	$P_r + 560$ ms	year 20	
57	$P_r + 570$ ms	year 40	
58	$P_r + 580$ ms	year 80	
59	$P_r + 590$ ms	position identifier 6 ( $P_6$ )	
60	$P_r + 600$ ms	index bit (0)	1 during the DST
61	$P_r + 610$ ms	index bit (0)	
62	$P_r + 620$ ms	Daylight Saving Pending (DSP)	
63	$P_r + 630$ ms	Daylight Saving Time (DST)	
64	$P_r + 640$ ms	Time Offset Sign (0=+, 1=-)	
65	$P_r + 650$ ms	Time Offset 1	
66	$P_r + 660$ ms	Time Offset 2	
67	$P_r + 670$ ms	Time Offset 4	
68	$P_r + 680$ ms	Time Offset 8	
69	$P_r + 690$ ms	position identifier 7 ( $P_7$ )	
70	$P_r + 700$ ms	Time Offset /2	between the local time and UTC (negative for West of Greenwich) between the local time and UTC (-12 ... +12)
71	$P_r + 710$ ms	Time Quality	
72	$P_r + 720$ ms	Time Quality	
73	$P_r + 730$ ms	Time Quality	
74	$P_r + 740$ ms	Time Quality	
75	$P_r + 750$ ms	Parity (odd)	
76	$P_r + 760$ ms	index bit (0)	
77	$P_r + 770$ ms	index bit (0)	

78	$P_r + 780$ ms	index bit (0)	seconds of the year (0 ... 86399 or 86400)
79	$P_r + 790$ ms	position identifier 8 ( $P_8$ )	
80	$P_r + 800$ ms	time-of-day 1	
81	$P_r + 810$ ms	time-of-day 2	
82	$P_r + 820$ ms	time-of-day 4	
83	$P_r + 830$ ms	time-of-day 8	
84	$P_r + 840$ ms	time-of-day 16	
85	$P_r + 850$ ms	time-of-day 32	
86	$P_r + 860$ ms	time-of-day 64	
87	$P_r + 870$ ms	time-of-day 128	
88	$P_r + 880$ ms	time-of-day 256	
89	$P_r + 890$ ms	position identifier 9 ( $P_9$ )	
90	$P_r + 900$ ms	time-of-day 512	
91	$P_r + 910$ ms	time-of-day 1024	
92	$P_r + 920$ ms	time-of-day 2048	
93	$P_r + 930$ ms	time-of-day 4096	
94	$P_r + 940$ ms	time-of-day 8192	
95	$P_r + 950$ ms	time-of-day 16384	
96	$P_r + 960$ ms	time-of-day 32768	
97	$P_r + 970$ ms	time-of-day 65536	
98	$P_r + 980$ ms	index bit (0)	
99	$P_r + 990$ ms	position identifier 0 ( $P_0$ )	

## APPENDIX B - Application Example

### Application example - Synchronism Outputs

In the Application example, shown in Figure 17, uses the three IRIG-B synchronism outputs via Ethernet network using NTP and PTP protocol and serial datagrams to synchronize relays and a disturbance recorder. It is also used an optical-electrical transceiver (RT412 - Optical transceiver) to transform an electrical output into optical when synchronizing a relay and a signal distributor (RT411 - Time Signal Distributor), that from a RT431 output, synchronizes 3 relays.

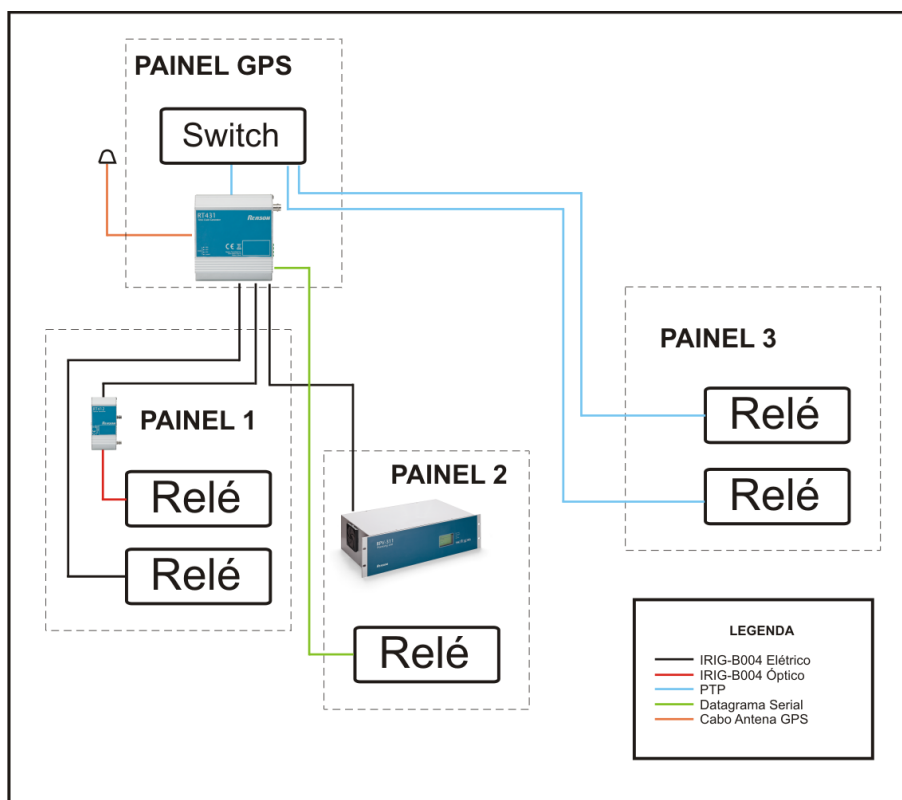


Figure 17: Application example - Synchronism Outputs